

# Shipdesign potential through autonomy in shipping







20 April 2021 Rolph Hijdra





# Independent design and engineering company

- Serving ship owners and shipyards worldwide
- 7 offices
- > 180 in-house engineers employed











## Autonomy as a tool



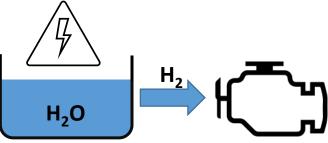














# Autonomous Guard Vessel (AGV)



Item	
Year of fabrication	1973
Loa x B	32 x 7 m
Engine power	750 kW
Max. speed	13 kn
Crew	5 pers.









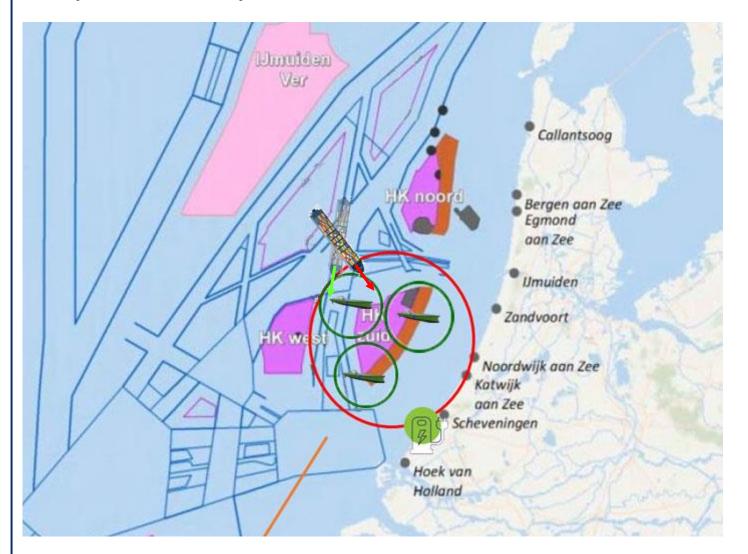








# Operational profile



Hollandse Kust Zuid

+
Typical Containerfeeder

+
Charging in port

+
Standby



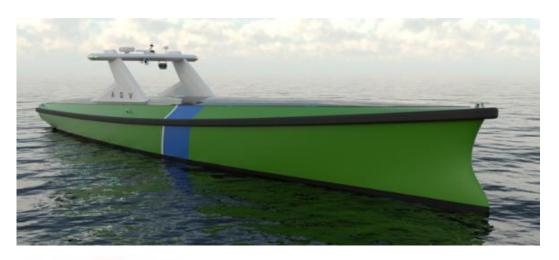
4 AGV's

**Intervention speed: 15 knots** 

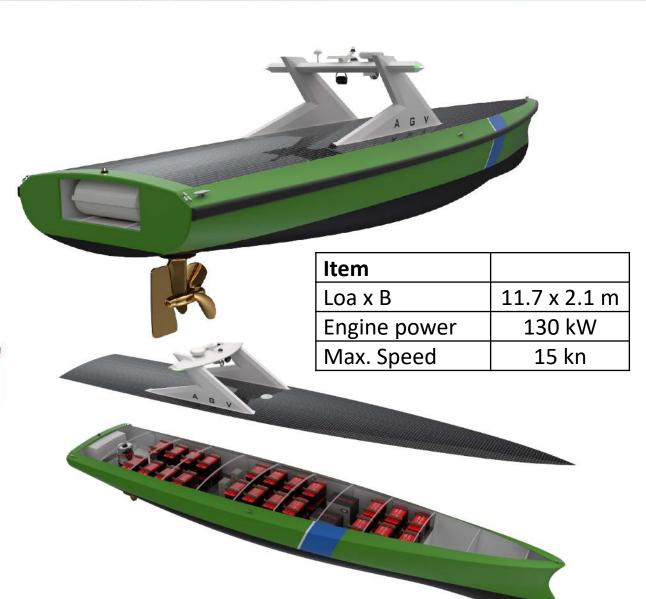
Batteries: ± 450 kWh



# Autonomous Guard Vessel (AGV)









# AGV vs Common practice







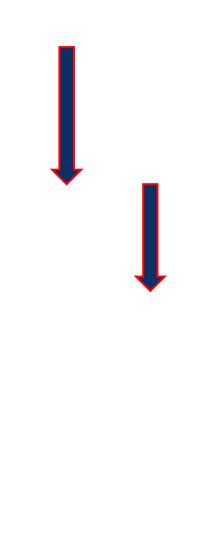






100 %

Total cost ≈





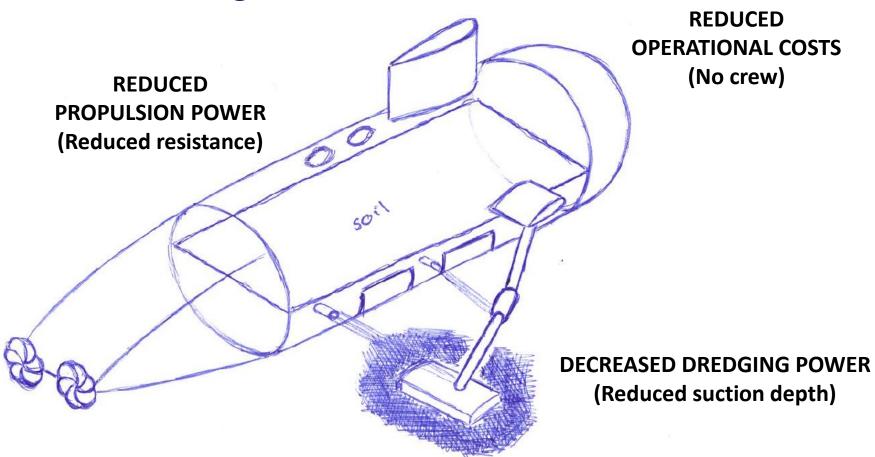
... Then, a completely different design



# Disruptive innovation: Autonomous submarine dredger

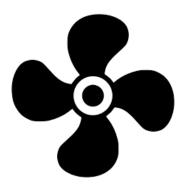


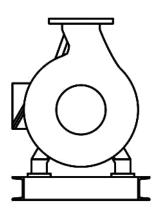
IMPROVED OPERABILITY (Submerged)





#### Power requirements





$$R_{total} = R_F (1 + k_1) + R_{app} + R_w + R_{TR}$$

$$R_F (1+ k_1) = Frictional resistance$$
 $R_{app} = Appendage resistance$ 
 $R_w = Wave making / -breaking resistance$ 
 $R_{TR} = Transom immersion resistance$ 

#### $2x 1100 \text{ kW (Conventional)} \rightarrow 2x 500 \text{ kW (AUMD)}$

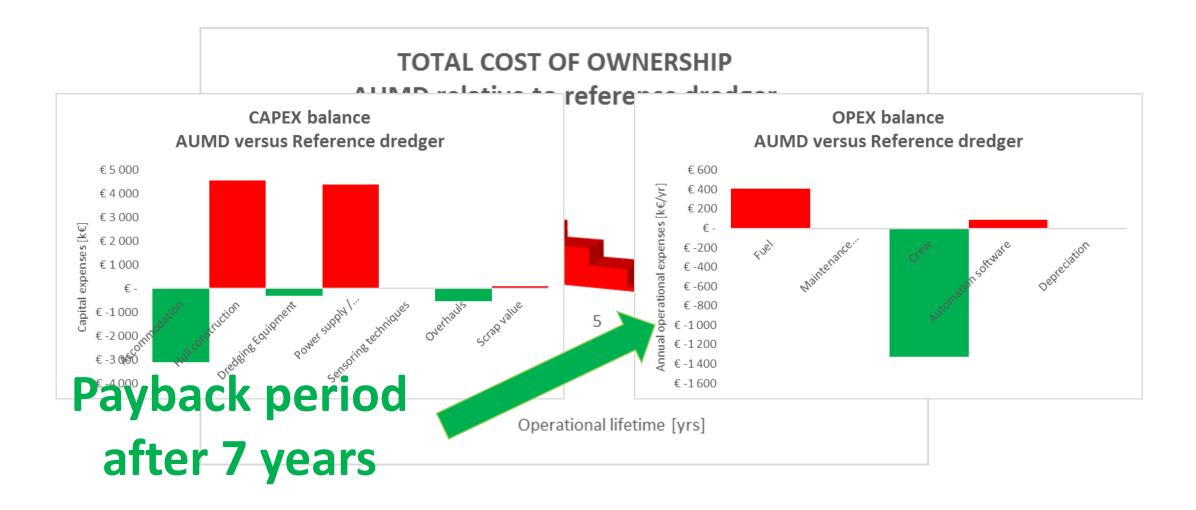
$$\Delta p_{loss,tot} = \Delta p_{su,loss} + \Delta p_{dis,loss} + p_{abs,dis} - p_{abs,draghead}$$

$$\Delta p_{su,loss}$$
 = Frictional loss + suction head, suction side  $\Delta p_{dis,loss}$  = Frictional loss + pressure head, discharge side  $\Delta p_{abs,dis}$  = Absolute pressure, discharge side  $\Delta p_{abs,draghead}$  = Absolute pressure, suction side

 $2x 675 \text{ kW (Conventional)} \rightarrow 2x 150 \text{ kW (AUMD)}$ 

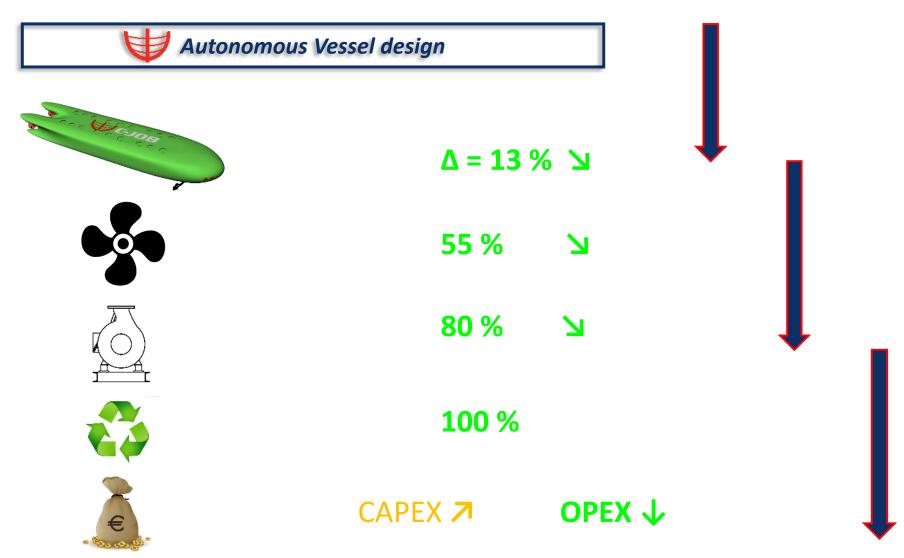


## Total cost of ownership





# **AUMD** vs Common practice





# Innovaties in de KustlijnZorg (IKZ)

Innovations in the Coastline Care

- Rijkswaterstaat selected AUMD version 2.0
- Innovation partnership
- Ambition ship ready by 2024
- Go / NoGo strategy









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